

Package Development in R: Implementing GO-GARCH models

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Introduction

Overview

- Task: From academic paper to implementation.
- Putting econometric methods/models into action.
- Design of a program structure that meets the needs of the user: form follows function.
- Helpful tools to fulfill this task.
- Example: Multivariate GARCH model class.

Introduction

Multivariate GARCH

Generally, a m -dimensional GARCH for a second-order stationary process $\{x_t\}$ is given as:

$$x_t | \mathcal{I}_{t-1} \sim \mathcal{D}(\phi, V_t), \quad (1)$$

whereby the information set up to time $t - 1$ is denoted by \mathcal{I}_{t-1} and the variance-covariance matrix V_t is time dependent. The information set contains lagged values of the squares and cross-products of x_t and elements of the conditional covariance matrices. The vector ϕ contains distribution dependent parameters. Ordinarily for \mathcal{D} a Normal distribution is assumed.

Introduction

Typology

According to the survey article of Bauwens *et al* (2006) multivariate GARCH models can be classified into three areas:

- Direct generalizations of the univariate GARCH model, *e.g.* VEC, BEKK and factor models.
- Linear combinations of univariate GARCH models, *e.g.* (generalized) orthogonal and latent factor GARCH models.
- Nonlinear combinations of univariate GARCH models, *e.g.* dynamic conditional correlation and general dynamic covariance models.

Introduction

Resources in R

- Univariate:¹
 - ① Package bayesGARCH (CRAN).
 - ② Rmetrics package fGarch (CRAN & R-Forge).
 - ③ Package rgarch (R-Forge).
 - ④ Function garch() in package tseries (CRAN).
- Multivariate:
 - ① Package ccgarch (CRAN).
 - ② Package gogarch (CRAN & R-Forge).
 - ③ Package rgarch (R-Forge).

¹For the sake of completeness a project rregrarch has been registered on R-Forge, but only an empty project skeleton exists as of the time this presentation is drafted.

GO-GARCH

Model

The observed m -dimensional economic process $\{x_t\}$ is governed by a linear combination of uncorrelated economic components $\{y_t\}$:

$$x_t = Zy_t \quad (2)$$

The linear map Z that links the unobserved components with the observed variables is assumed to be constant over time, and invertible. The unobserved components are normalized to have unit variance, such that:

$$V = \mathbb{E}[x_t x_t'] = ZZ' \quad (3)$$

GO-GARCH

Example GO-GARCH(1, 1)

An explicit example, whereby the Normal distribution is assumed would then be:

$$x_t = Zy_t \text{ with } y_t \sim \mathcal{N}(0, H_t) \quad (4)$$

and each component is described by a GARCH(1, 1) process:

$$H_t = \text{diag}(h_{1,t}, \dots, h_{m,t}) \quad (5)$$

$$h_{i,t} = \omega_i + \alpha_i y_{i,t-1}^2 + \beta_i h_{i,t-1}, \text{ for } i = 1, \dots, m \quad (6)$$

The unconditional covariance matrix of the components is $H_0 = I$ and the conditional covariances of $\{x_t\}$ are given by $V_t = ZH_tZ'$.

GO-GARCH

The quest for Z , part I

Let Z be the map that links the uncorrelated components $\{y_t\}$ with the observed process $\{x_t\}$. Then there exists an orthogonal matrix U_0 such that:

$$P\Delta^{\frac{1}{2}}U_0 = Z \quad (7)$$

The matrices P and $\Delta^{\frac{1}{2}}$ can be retrieved by SVD from sample information, *i.e.*, the unconditional variance/covariance matrix of $\{x_t\}$.

And what about U_0 ?

GO-GARCH

The quest for Z, part II

One parametrization of U is given as follows:

Every m -dimensional orthogonal matrix U with $\det(U) = 1$ can be represented as a product of $\binom{m}{2} = [m(m-1)]/2$ rotation matrices:

$$U = \prod_{i < j} R_{ij}(\theta_{ij}) \text{ with } -\pi \leq \theta_{ij} \leq \pi, \quad (8)$$

where $R_{ij}(\theta_{ij})$ performs a rotation in the plane spanned by e_i and e_j over an angle θ_{ij} ; the so-called Euler angles.

GO-GARCH

Estimation by ...

- Maximum-Likelihood, see van der Weide (2002).
- Non-linear Least-Squares, see Boswijk and van der Weide (2006).
- Methods-of-Moments, see Boswijk and van der Weide (2009).
- Fast ICA, see Broda and Paoletta (2008).

Design

Guidelines

- Think of a model class in terms of an object, *i.e.*, GO-GARCH.
- Write methods for estimating your model, retrieving and/or displaying items from that object.
- Provide the user with as many options for a tailor-made usage.
- Adhere to a naming convention for classes and functions.
- Error checking and handling as early as possible.
- Use coercing where appropriate and possible.
- Employ checks, tests and/or validation.

Design

Classes

- Class definition for orthogonal matrices: *Orthom*.
- Class for initial model object: *Goinit*.
- Class for GO-GARCH models: *GoGARCH* (inherits from *Goinit*)
- Dependent upon the chosen estimation method (inherits from *GoGARCH*):
 - 1 Fast ICA: *Goestica*
 - 2 Methods of Moments: *Goestmm*
 - 3 Maximum-Likelihood: *Goestml*
 - 4 Non-linear Least-Squares: *Goestnls*
- Class for summary objects: *Gosum*
- Class for predict objects: *Gopredict*

Design

Methods

Think of methods as the answers to the question: “What does the user wants or is interested in?”.

- Estimation (goest) and displaying the result, *i.e.*, show, print, summary.
- Displaying the result graphically, *i.e.*, plot.
- Update the model's structure and/or estimation method, *i.e.*, update.
- Retrieval the conditional variances, *i.e.*, cvar, ccor, ccov.
- Calculate forecasts, *i.e.*, predict, and the predicted conditional variances should be made available (cvar, ccor, ccov).

Design

Functions

- Main functions for creating objects of a certain formal class: `gogarch` and `goinit`.
- Auxiliary functions for clearer code appearance, *i.e.* objective function to optimize (`gollh`, `gonls`), manipulation of objects (`unvech`, `Umatch`, `UprodR`, `Rd2`, `gotheta`).
- Validation: `validGoinitObject` for objects of class *Goinit* and `validOrthomObject` for objects of class *Orthom*.

Hint: Prefix function's name with a dot if it should not be documented in a package.

Implementation

Key Points

- Package gogarch purely written in R.
- Current version 0.6-9 as of 2009-04-28.
- S4 classes/methods and NAMESPACE employed.
- Dependencies: R ($\geq 2.7.0$), methods, stats, graphics, fGarch, fastICA
- License: GPL (≥ 2)
- Available at:
 - 1 <http://cran.r-project.org>
 - 2 <http://r-forge.r-project.org/projects/gogarch/>
 - 3 <http://www.pfaffikus.de>

Implementation

Guidelines

- Release your code early and often.
- Package your code as early as possible.
- Employ a source control software, e.g. Subversion.
- Document your code (within the functions and in form of a manual).
- Provide examples and/or a “How to” and/or a vignette.
- Publicize your package, e.g. JSS <http://www.jstatsoft.org/>.
- If possible, replicate trustworthy results from published articles.

Implementation

Package's Structure

Methods	Classes								
	Goinit	GoGARCH	Goestica	Goestmm	Goestml	Goestnls	Gosum	Gopredict	Orthom
angles					x				
ccor		x	x	x	x	x		x	
ccov		x	x	x	x	x		x	
converged		x	x	x	x	x			
coef		x	x	x	x	x			
cvar		x	x	x	x	x		x	
formula		x	x	x	x	x			
logLik					x				
M									x
plot		x	x	x	x	x			
predict		x	x	x	x	x			
print									x
resid		x	x	x	x	x			
residuals		x	x	x	x	x			
show	x	x	x	x	x	x	x	x	x
summary		x	x	x	x	x			
t									x
update		x	x	x	x	x			

Implementation

Economic coding, Ia

```
> getMethod("coef", "GoGARCH")
```

Method Definition:

```
function (object, ...)
{
  .local <- function (object)
  {
    garchc <- matrix(unlist(lapply(object@models, coef)),
      nrow = ncol(object@X), byrow = TRUE)
    colnames(garchc) <- names(object@models[[1]]@fit$par)
    rownames(garchc) <- paste("y", 1:nrow(garchc), sep = "")
    return(garchc)
  }
  .local(object, ...)
}
<environment: namespace:gogarch>
```

Signatures:

```
      object
target "GoGARCH"
defined "GoGARCH"
```

Implementation

Economic coding, IIb

Due to inheritance one only needs:

```
> getMethod("coef", "Goestmm")
```

Method Definition:

```
function (object, ...)
{
  .local <- function (object)
  {
    callNextMethod()
  }
  .local(object, ...)
}
<environment: namespace:gogarch>
```

Signatures:

```
      object
target "Goestmm"
defined "Goestmm"
```

which results from the sources:

```
setMethod(f = "coef", signature(object = "Goestmm"), definition = function(object){
  callNextMethod()
})
```

Implementation

Economic coding, IIa

```
> getMethod("cvar", "GoGARCH")
```

Method Definition:

```
function (object, ...)
{
  .local <- function (object)
  {
    m <- ncol(object@X)
    n <- nrow(object@X)
    cvar <- matrix(c(unlist(lapply(object@H, function(x) diag(x)))),
      ncol = m, nrow = n, byrow = TRUE)
    colnames(cvar) <- paste("V.", colnames(object@X), sep = "")
    rownames(cvar) <- rownames(object@X)
    cvar <- as.ts(cvar)
    return(cvar)
  }
  .local(object, ...)
}
<environment: namespace:gogarch>
```

Signatures:

```
object
target "GoGARCH"
defined "GoGARCH"
```

Implementation

Economic coding, IIb

Due to inheritance one only needs:

```
> getMethod("cvar", "Goestmm")
```

Method Definition:

```
function (object, ...)
{
  .local <- function (object)
  {
    cvar(as(object, "GoGARCH"))
  }
  .local(object, ...)
}
<environment: namespace:gogarch>
```

Signatures:

```
      object
target "Goestmm"
defined "Goestmm"
```

which results from the sources:

```
setMethod(f = "cvar", signature(object = "Goestmm"), definition = function(object){
  cvar(as(object, "GoGARCH"))
})
```

Implementation

Example 1a, van der Weide (2002)

```
> library(gogarch)
> library(vars)
> data(VDW)
> var1 <- VAR(scale(VDW), p = 1,
+           type = "const")
> resid <- residuals(var1)
> gogml <- gogarch(resid, ~garch(1, 1),
+           scale = TRUE, estby = "ml",
+           control = list(iter.max = 1000))
> gogml
> solve(gogml@Z)
> plot(gogml)
```

```
*****
*** GO-GARCH ***
*****
```

Components estimated by: maximum likelihood
 Dimension of data matrix: (3081 x 2).
 Formula for component GARCH models: ~ garch(1, 1)

Orthogonal Matrix U:

```
          [,1]      [,2]
[1,] 0.6554845 -0.7552086
[2,] 0.7552086  0.6554845
```

Linear Map Z:

```
          [,1]      [,2]
[1,] -0.2766742 -0.9607949
[2,] -0.9123173 -0.4090874
```

Estimated GARCH coefficients:

```
          omega      alpha1      beta1
y1 0.003037073 0.09098498 0.9071785
y2 0.010014348 0.05231209 0.9401891
```

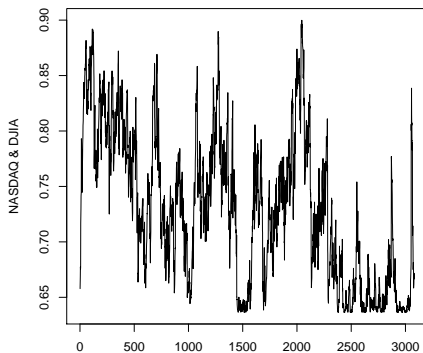
Convergence codes of component GARCH models:

```
y1 y2
 1  1
```

Implementation

Example Ib, van der Weide (2002)

Conditional correlations between NASDAQ & Dow Jones



Implementation

Example II, Boswijk and van der Weide (2006)

```
> data(BVDW)
> BVDW <- zoo(x = BVDW[, -1],
+           order.by = BVDW[, 1])
> BVDW <- diff(log(BVDW)) * 100
> gognls <- gogarch(BVDW, formula =
+             ~garch(1,1), scale = TRUE,
+             estby = "nls")
> gognls
```

```
*****
*** GO-GARCH ***
*****
```

```
Components estimated by: non-linear Least-Squares
Dimension of data matrix: (2609 x 2).
Formula for component GARCH models: ~ garch(1, 1)
```

Orthogonal Matrix U:

```
           [,1]      [,2]
[1,] -0.5241201 -0.8516443
[2,]  0.8516443 -0.5241201
```

Linear Map Z:

```
           [,1]      [,2]
[1,] 0.8141711 -0.5802948
[2,] 0.1511830 -0.9883119
```

Estimated GARCH coefficients:

```
           omega      alpha      beta1
y1 0.009343703 0.08749236 0.9049185
y2 0.005866510 0.04367927 0.9520289
```

Convergence codes of component GARCH models:

```
y1 y2
1  1
```

Implementation

Example III, Boswijk and van der Weide (2009)

```
> data(BVDWSTOXX)
> BVDWSTOXX <- zoo(x = BVDWSTOXX[, -1],
+               order.by = BVDWSTOXX[, 1])
> BVDWSTOXX <- window(BVDWSTOXX,
+                   end = as.POSIXct("2007-12-31"))
> BVDWSTOXX <- diff(log(BVDWSTOXX))
> sectors <- BVDWSTOXX[, c("AutoParts",
+                          "Banks", "OilGas")]
> sectors <- apply(sectors, 2, scale,
+                 scale = FALSE)
> gogmm <- gogarch(sectors, formula =
+               ~garch(1,1), estby = "mm",
+               lag.max = 100)
> gogmm
```

```
*****
*** GO-GARCH ***
*****
```

```
Components estimated by: Methods of Moments
Dimension of data matrix: (5420 x 3).
Formula for component GARCH models: ~ garch(1, 1)
```

Orthogonal Matrix U:

	[,1]	[,2]	[,3]
[1,]	0.97243228	-0.1580023	0.1714956
[2,]	0.04054402	0.8388089	0.5429142
[3,]	-0.22963370	-0.5209942	0.8220909

Linear Map Z:

	[,1]	[,2]	[,3]
[1,]	0.012150308	0.006416573	-0.003053992
[2,]	0.003914599	0.010216543	-0.003626263
[3,]	0.004364691	0.008865709	0.006737270

Estimated GARCH coefficients:

	omega	alpha1	beta1
y1	0.013982146	0.06081926	0.9256579
y2	0.003267435	0.04320838	0.9542282
y3	0.021353037	0.07085826	0.9065798

Convergence codes of component GARCH models:

y1	y2	y3
1	1	1

Literature

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